

#### Lecture 4 Theory of Deep Learning

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# **Key Elements in Neural Network**

- Activation Function
- Softmax Function
- Mathematical Expression for Network Function
- Learning Rate
- Gradient Descent
- Momentum
- Maxout
- Dropout

#### **Single Neuron**





#### **Activation Function**



#### **Various Activation Function**



Leaky ReLU: 
$$f(x) = \max(\alpha x, x)$$

$$\max(w_1^T x + b_1, w_2^T x + b_2)$$

$$\mathsf{ELU}: f(x) = \begin{cases} x & x \ge 0\\ \alpha(e^x - 1) & x < 0 \end{cases}$$

## ReLU

• Rectifier Linear Unit



## ReLU



### **Output Layer**

• Softmax Layer

$$y_{1} = e^{z_{1}} / \sum_{j=1}^{3} e^{z_{j}}$$
$$y_{2} = e^{z_{2}} / \sum_{j=1}^{3} e^{z_{j}}$$
$$y_{3} = e^{z_{3}} / \sum_{j=1}^{3} e^{z_{j}}$$

model.add( Dense(output\_dim=10 )
model.add( Activation('softmax')

model2.add(Dense(output\_dim=100))
model2.add(Activation('relu'))
model2.add(Dense(output\_dim=10))
model2.add(Activation('softmax'))

## **Activation Functions**



$$z_i^{l} = w_{i1}^{l} a_1^{l-1} + w_{i2}^{l} a_2^{l-1} \dots + b_i^{l}$$









 $z^{l} = W^{l}a^{l-1} + b^{l}$  $a^{l} = \sigma(z^{l})$  $a^{l} = \sigma(W^{l}a^{l-1} + b^{l})$ 

Layer l-1 $N_{l-1}$  nodes Layer l $N_l$  nodes

#### **Functions of Neural Network**



## **Uniform Expression**



### **Good Function = Loss as Small as Possible**

A good function should make the loss of all examples as small as possible.



## **Loss Functions**

• Square Error: 
$$\sum_{i=1}^{10} (y_i - \hat{y}_i)^2 \qquad \begin{array}{c} \text{model.compile(loss='mse', optimizer=SGD(lr=0.1), \\ metrics=['accuracy'])} \end{array}$$

• Cross-entropy
$$-\sum_{i=1}^{10} \widehat{y}_i ln y_i$$

- -

function set

$$y = f(x) = \sigma(\mathbf{W}^L \dots \sigma(\mathbf{W}^2 \sigma(\mathbf{W}^1 x + b^1) + b^1) \dots + b^L)$$

because different parameters W and b lead to different function

Formal way to define a function set:

 $f(x;\underline{\theta}) \rightarrow \text{parameter set}$  $\theta = \left\{ W^1, b^1, W^2, b^2 \cdots W^L, b^L \right\}$ 



## **How to Determine Parameters**

#### Find *network parameters* $\theta^*$ that minimize total loss L

Enumerate all possible values

Network parameters  $\theta = \{w_1, w_2, w_3, \cdots, b_1, b_2, b_3, \cdots\}$ 

Millions of parameters

E.g. speech recognition: 8 layers and 1000 neurons each layer





Network parameters  $\theta = \{w_1, w_2, \cdots, b_1, b_2, \cdots\}$ 





Until  $\partial L / \partial w$  is approximately small



#### Randomly pick up a start point



## Local Minima



## Local Minima



#### **Different initial points reach different local minima!**

## **Local Minima**



#### If learning rate is too large, total loss may not decrease

# **Learning Rate**



$$w \leftarrow w - \eta \partial L / \partial w$$

#### If learning rate is too small, training would be too slow!

# **Learning Rate**

- At the beginning, we can set a large learning rate
- After several epochs, we reduce the learning rate
- Giving different parameters different learning rate

## Momentum



How about put this phenomenon in gradient descent

### Momentum



metrics=['accuracy'])

## Dropout

**Training:** 



Each neuron has p% to dropout in each epoch!

model.add( dropout(0.8) )

## Maxout



### **In Practice**

